

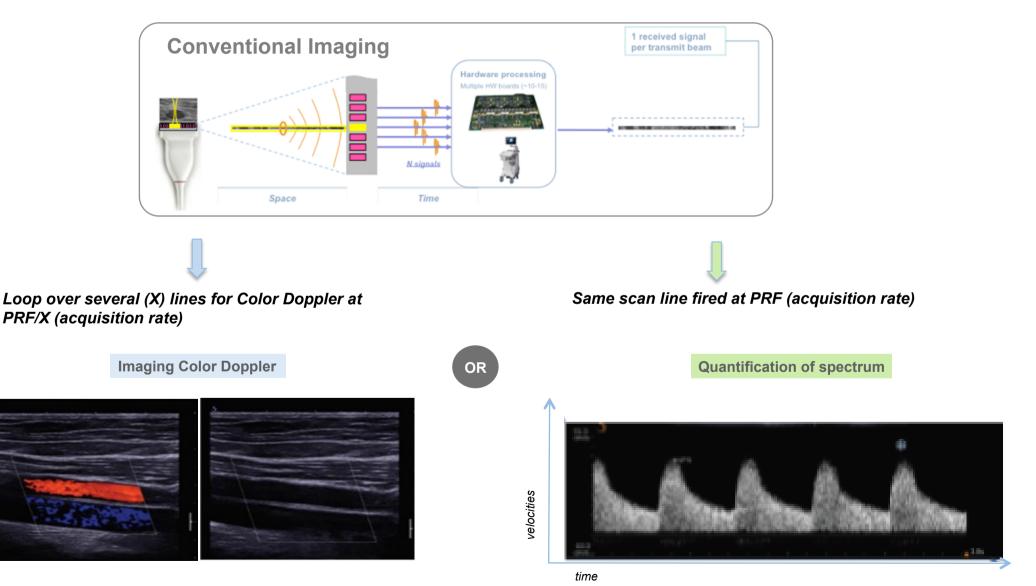
Slides to support subcommittee focusing on the quantification and not imaging: analogy with Doppler

- Telco of June 8th: discussion of imaging versus quantification: we need to focus on Quantification
- This presentation aims at strengthening this point: focus on quantification (versus imaging using the analogy of Doppler) and discuss sources of system dependencies as follows:
- Differentiate ROI definition amongst systems:
 - zone for fibroscan
 - window for Siemens, Philips (others?)
 - ROI defined on an image
- Differentiate SWE methodologies based on the key steps of Elastography:
 - Constraint generation
 - Measurement of displacements and shear Wave velocities
 - Estimation of young's modulus (inverse problem)

Tradeoff for conventional ultrasound imaging: rate of acquisition versus imaging/acquisition area



- Imaging using transmit and receive focusing: each transmit receive event is imaging one scan line
- The higher the number of lines the lower the framerate (zone-rate)



Mean velocity (central frequency) in a colour coded image representation

Quantification of velocity in 1 single location using

Claude COHEN-BACRIE, SuperSonic Imaginspectrum analysis



Doppler acquisition requirements depend on velocity estimator

- Mean frequency for Color Doppler using Autocorrelation as an estimator
- Full spectrum for Spectral Doppler: FFT of highly sampled Doppler signal as an estimator
- Each estimator requires its specific acquisition protocol

Elastography estimators for static and transient elastography

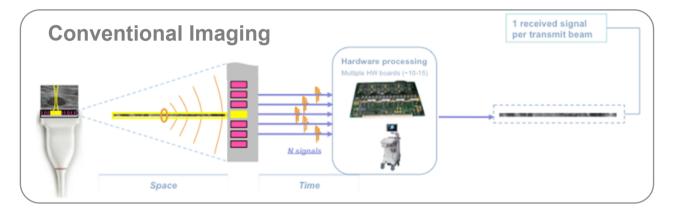
- Elastography is an indirect method: inverse problem: y = Hx y, observations; x young's modulus
- 2 physical phenomenon: deformation (static) under a constraint versus shearwave propagation (transient)
- Use of direct measurement y is used for both Static and SWE:
 - Deformation estimates stiffness in a qualitative manner for static Elastography (H is a full matrix)
 - ShearWave velocity estimates stiffness in a quantitative manner for transient Elastography (H is a diagonal)

As long as we measure velocity we donot need to consider inversion of H in the system dependencies.

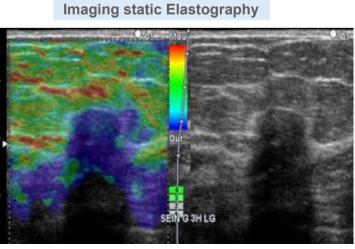
Strain imaging and SWE have different acquisition constraints



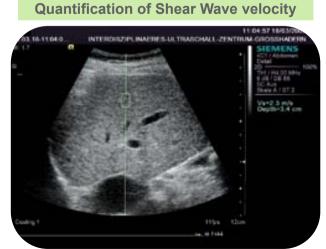
- Rate of deformation can be measured while looping scan lines
- Shearwave propagation velocities requires high acquisition rate



Loop over several (X) lines for Static Elastography at PRF/X (acquisition rate)



Same line(s) fired at PRF (acquisition rate) or few lines (4x) scanned at PRF/4

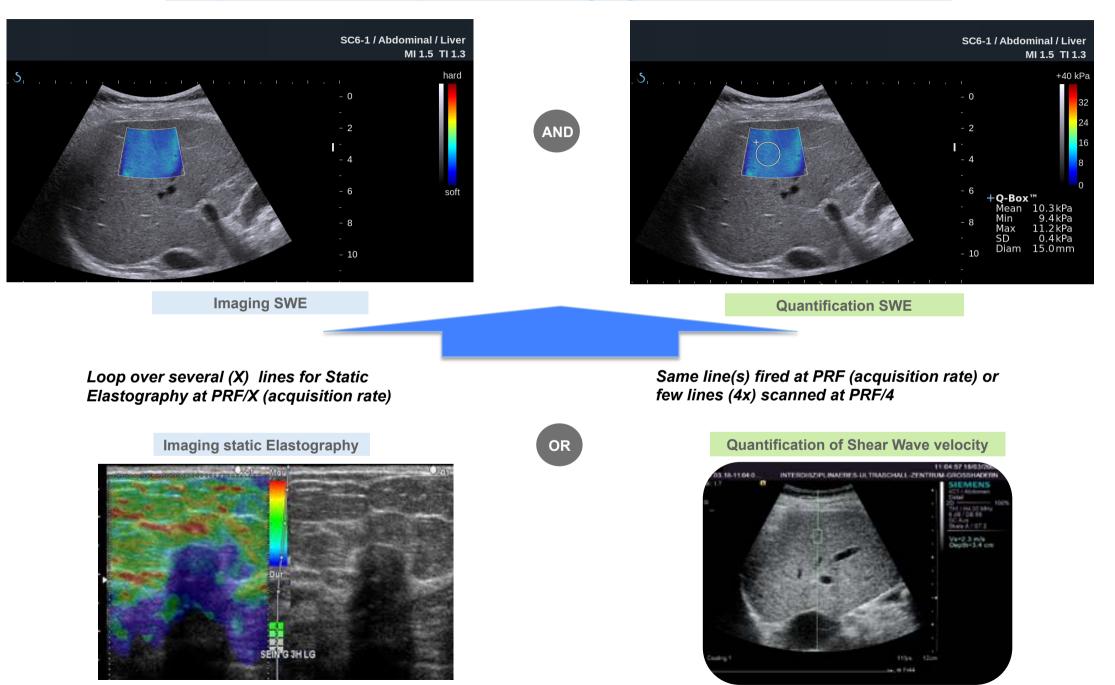


Strain imaging using derivative of tissue Doppler COHEN-BACRIE, SuperSonic Imagine Quantification of velocity in 1 given location

OR



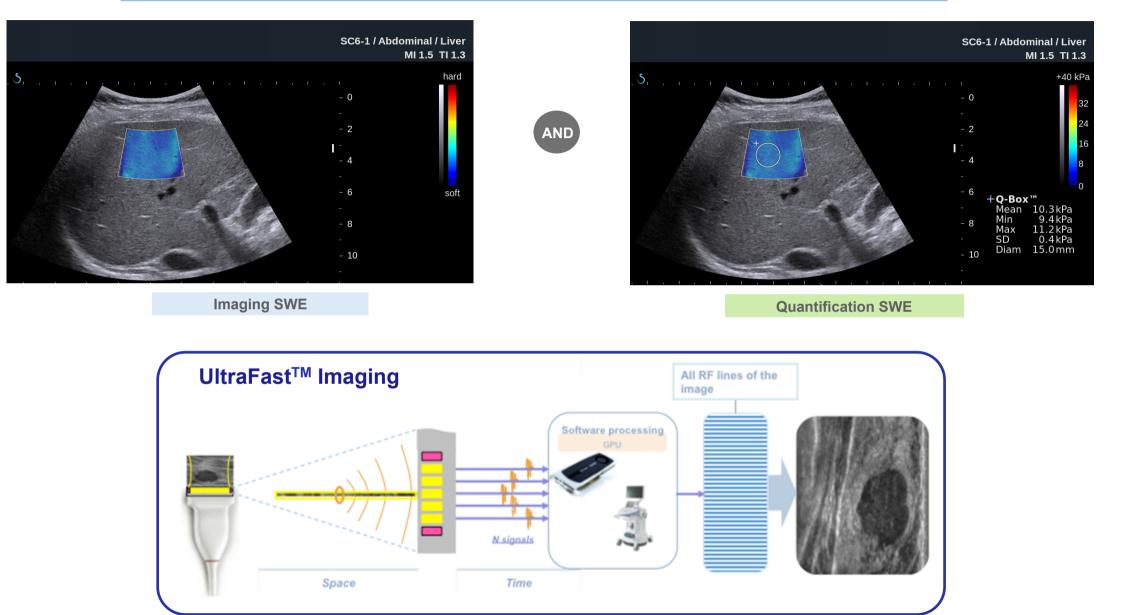
SuperSonic SWE provides imaging AND Quantification



Strain imaging using derivative of tissue Doppler de COHEN-BACRIE, SuperSonic Imagine Quantification of velocity in 1 given location

Highly parallel imaging overcomes the limits of conventional imaging and tradeoff between imaging and quantification

imagine



Debate and system dependancies should be focused on quantification NOT on Imaging



- Method of measurement depend on
 - Region of Interest definition
 - zone for fibroscan
 - window like spectral window
 - ROI defined on an image
 - SWE methodology
 - Constraint generation: pushgeneration; frequency content; source geometry; temporal length; impulsive; repeated, modulated; , Etc..
 - Measurement method
 - Scanning method: (scan lines (conventional imaging), zone acquisition (Fibroscan), multiline or ultrafast imaging); PRF, spacing of tracking beams, etc..;
 - Displacement measurement method (tissue Doppler methods)
 - Shear wave velocity estimation (correlation, etc..)
 - Estimation (if conversion in kPa) or not (ShearWave Velocity) which depends on Wave Physics model (assumptions on shear wave propagation)
- Recommendation to use these categories to list system dependencies in an exhaustive way